



TEXAS ADVANCED COMPUTING CENTER

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TEXAS

The University of Texas at Austin

Python 101/201

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Science in the Cloud, 2019

Agenda

- Introduction to the Jupyter Notebook
- Welcome to Python
- Linear Algebra refresh
- Using Numpy

What are Jupyter Notebooks?

A web-based, interactive computing tool for capturing the whole computation process: developing, documenting, and executing code, as well as communicating the results.

How do Jupyter Notebooks Work?

An open notebook has exactly one interactive session connected to a kernel which will execute code sent by the user and communicate back results. This kernel remains active if the web browser window is closed, and reopening the same notebook from the dashboard will reconnect the web application to the same kernel.

What's this mean?

Notebooks are an interface to kernel, the kernel executes your code and outputs back to you through the notebook. The kernel is essentially our programming language we wish to interface with.

Jupyter Notebooks, Structure

- Code Cells

Code cells allow you to enter and run code
Run a code cell using Shift-Enter

- Markdown Cells

Text can be added to Jupyter Notebooks using Markdown cells.
Markdown is a popular markup language that is a superset of HTML.

Jupyter Notebooks, Structure

- **Markdown Cells**

You can add headings:

- # Heading 1
- # Heading 2
- ## Heading 2.1
- ## Heading 2.2

You can add lists

- 1. First ordered list item
- 2. Another item
 - · * Unordered sub-list.
- 1. Actual numbers don't matter, just that it's a number
 - · 1. Ordered sub-list
- 4. And another item.

Jupyter Notebooks, Structure

- Markdown Cells

pure HTML

```
<dl>
```

```
<dt>Definition list</dt>
```

```
<dd>Is something people use sometimes.</dd>
```

```
<dt>Markdown in HTML</dt>
```

```
<dd>Does not work very well. Use HTML tags.</dd>
```

```
</dl>
```

And even, Latex!

```

$$e^{i\pi} + 1 = 0$$

```

Jupyter Notebooks, Workflow

Typically, you will work on a computational problem in pieces, organizing related ideas into cells and moving forward once previous parts work correctly. This is much more convenient for interactive exploration than breaking up a computation into scripts that must be executed together, as was previously necessary, especially if parts of them take a long time to run.

Jupyter Notebooks, Workflow

Let a traditional paper lab notebook be your guide:

Each notebook keeps a historical (and dated) record of the analysis as it's being explored.

The notebook is not meant to be anything other than a place for experimentation and development.

Notebooks can be split when they get too long.

Notebooks can be split by topic, if it makes sense.

Jupyter Notebooks, Shortcuts

- **Shift-Enter**: run cell
 - Execute the current cell, show output (if any), and jump to the next cell below. If **Shift-Enter** is invoked on the last cell, a new code cell will also be created. Note that in the notebook, typing **Enter** on its own *never* forces execution, but rather just inserts a new line in the current cell. **Shift-Enter** is equivalent to clicking the **Cell | Run** menu item.

Jupyter Notebooks, Shortcuts

- **Ctrl-Enter**: run cell in-place
 - Execute the current cell as if it were in “terminal mode”, where any output is shown, but the cursor *remains* in the current cell. The cell’s entire contents are selected after execution, so you can just start typing and only the new input will be in the cell. This is convenient for doing quick experiments in place, or for querying things like filesystem content, without needing to create additional cells that you may not want to be saved in the notebook.

Jupyter Notebooks, Shortcuts

- **Alt-Enter**: run cell, insert below
 - Executes the current cell, shows the output, and inserts a *new* cell between the current cell and the cell below (if one exists). (shortcut for the sequence **Shift-Enter**, **Ctrl-m a**. (**Ctrl-m a** adds a new cell above the current one.))
- **Esc and Enter**: Command mode and edit mode
 - In command mode, you can easily navigate around the notebook using keyboard shortcuts. In edit mode, you can edit text in cells.

Introduction to Python

Hello World!

Data types

Variables

Arithmetic operations

Relational operations

Input/Output

Control Flow

Do not forget:

Indentation matters!

Python

```
print("Hello World!")
```

Let's type that line of code into a Code Cell, and hit Shift-Enter:

Hello World!

Python

```
print(5)
```

```
print(1+1)
```

Let's add the above into another Code Cell, and hit Shift-Enter

5

2

Python - Variables

You will need to store data into variables

You can use those variables later on

You can perform operations with those variables

Variables are declared with a **name**, followed by '=' and a **value**

An integer, string,...

When declaring a variable, **capitalization** is important:

'A' <> 'a'

Python - Variables

in a code cell:

```
five = 5
one = 1
twodot = 2.0
print (five)
print (one + one)
message = "This is a string"
print (message)
```

Notice: We're not "typing" our variables, we're just setting them and allowing Python to type them for us.

Python - Data Types

in a code cell:

```
integer_variable = 100  
floating_point_variable = 100.0  
string_variable = "Name"
```

Notice: We're not "typing" our variables, we're just setting them and allowing Python to type them for us.

Python - Data Types

Variables have a type

You can check the type of a variable by using the `type()` function:

```
print (type(integer_variable))
```

It is also possible to change the type of some basic types:

`str(int/float)`: converts an integer/float to a string

`int(str)`: converts a string to an integer

`float(str)`: converts a string to a float

Be careful: you can only convert data that actually makes sense to be transformed

Python - Arithmetic Operations

+	Addition	$1 + 1 = 2$
-	Subtraction	$5 - 3 = 2$
/	Division	$4 / 2 = 2$
%	Modulo	$5 \% 2 = 1$
*	Multiplication	$5 * 2 = 10$
//	Floor division	$5 // 2 = 2$
**	To the power of	$2 ** 3 = 8$

Python - Arithmetic Operations

Some experiments:

```
print (5/2)
print (5.0/2)
print ("hello" + "world")
print ("some" + 1)
print ("number" * 5)
print (3+5*2)
```

Python - Arithmetic Operations

Some more experiments:

```
number1 = 5.0/2
```

```
number2 = 5/2
```

what **type()** are they?

```
type(number1)
```

```
type(number2)
```

now, convert number2 to an integer:

```
int(number2)
```

Python - Reading from the Keyboard

Let put the following into a new Code Cell:

```
numIn = input("Please enter a number: ")
```

Let's run this cell!

Python - Reading from the Keyboard

Let put the following into a new Code Cell:

```
stringIn = input("Please enter a string: ")
```

Let's run this cell!

put the word **Hello** as your input.

What happened?

Python - Making the output prettier

Let put the following into a new Code Cell:

```
print ("The number that you wrote was : ", numIn)
print ("The number that you wrote was : %d" % numIn)
```

```
print ("the string you entered was: ", stringIn)
print ("the string you entered was: %s" % stringIn)
```

Want to make it prettier?

\n for a new line

\t to insert a tab

```
print (" your string: %s\n your number: %d", %(numIn, stringIn))
```

for floating points, use %f

Python - Writing to a File

Let put the following into a new Code Cell:

```
my_file = open("output_file.txt", 'w')
var1 = "This is a string\n"
my_file.write(var1)
var2 = 10
my_file.write("\n")
my_file.write(str(var2))
var3 = 20.0
my_file.write("\n")
my_file.write(str(var3))
my_file.close()
```

Python - Reading from a File

When opening a file, you need to decide “how” you want to open it:

Just read?

Are you going to write to the file?

If the file already exists, what do you want to do with it?

r read only (default)

w write mode: file will be overwritten if it already exists

a append mode: data will be appended to the existing file

Python - Reading from a File

Let's read from the file we created in the previous cell.

```
my_file = open("output_file.txt",'r')
content = my_file.read()
print(content)
my_file.close()
```

Python - Reading from a File

Let's read it line by line

```
my_file = open("output_file.txt", 'r')
var1 = my_file.readline()
var2 = my_file.readline()
var3 = my_file.readline()
var4 = my_file.readline()
print("String: ", var1)
print("Blank: ", var2)
print("Integer: ", var3)
print("Float: ", var4)
my_file.close()
```

Python - Reading from a File

Tweak it a bit to make the code easier to read... introducing 'with'!

'with' will very nicely close your file for you

(Note the indentation!!)

```
with open("output_file.txt", 'r') as f:  
    var5 = f.readline()  
    var6 = f.readline()  
    var7 = f.readline()  
    var 8 = f.readline()  
    print("String: ", var5)  
    print("Blank: ", var6)  
    print("Integer: ", var7)  
    print("Float: ", var8)
```

Python - Control Flow

So far we have been writing instruction after instruction where every instruction is executed

What happens if we want to have instructions that are only executed if a given condition is true?

Python - if/else/elif

Let's look at some example of booleans.

type the following into a code cell

```
a = 2
```

```
b = 5
```

```
print (a>b)
```

```
print (a<b)
```

```
print (a == b)
```

```
print (a != b)
```

```
print (b>a or a==b)
```

```
print (b<a and a==b)
```


Python - if/else/elif

The if/else construction allows you to define conditions in your program

(Don't forget your indentation!!)

```
if conditionA:  
    statementA  
elif conditionB:  
    statementB  
else:  
    statementD  
this line will always be executed (after the if/else)
```

Python - *if/else/elif*

The if/else construction allows you to define conditions in your program

(Indentation is IMPORTANT!)

```
if conditionA:  
    statementA  
elif conditionB:  
    statementB  
else:  
    statementD  
this line will always be executed (after the if/else)
```

conditions are a datatype known as booleans, they can only be true or false

Python - if/else/elif

A simple example

```
simple_input = input("Please enter a number: ")
if (int(simple_input)>10):
    print ("You entered a number greater than 10")
else:
    print ("you entered a number less than 10")
```

Python - if/else/elif

You can also nest if statements together:

```
if (condition1):
    statement1
    if (condition2):
        statement2
    else:
        if (condition3):
            statement3 # when is this statement executed?
else: # which 'if' does this 'else' belong to?
    statement4 # when is this statement executed?
```

Exercise:

enter a number from the keyboard into a variable.

using type casting and if statements, determine if the number is even or odd

Python - For Loops

When we need to iterate, execute the same set of instructions over and over again... we need to loop! and introducing range()

(Indentation is IMPORTANT!)

```
for x in range(0, 3):  
    print ("Let's go %d" % x)
```

Python - For Loops, nested loops

When we need to iterate, execute the same set of instructions over and over again... we need to loop! and introducing range()

```
for x in range(0, 3):  
    for y in range(0,5):  
        print ("Let's go %d %d" % (x,y))
```

Exercise:

using nested for-loops and nested if statements, write a program that loops from 3 to 1000 and print out the number if it is a prime number.

Exercise:

using a for loop, find the triples that satisfies:

$$a*a + b*b = c*c$$

where

$$0 < a < 100$$

$$0 < b < 100$$

Python - While Loops

Sometimes we need to loop while a condition is true...

(remember to indent!)

```
i = 0           # Initialization
while (i < 10): # Condition
    print (i)   # do_something
    i = i + 1   # Why do we need this?
```

Exercise:

using a while loop, find the prime numbers less than 1000

Python - lists

A list is a sequence, where each element is assigned a position (index)
First position is 0. You can access each position using []
Elements in the list can be of different type

```
mylist1 = ["first item", "second item"]
mylist2 = [1, 2, 3, 4]
mylist3 = ["first", "second", 3]
print(mylist1[0], mylist1[1])
print(mylist2[0])
print(mylist3)
print(mylist3[0], mylist3[1], mylist3[2])
print(mylist2[0] + mylist3[2])
```

Python - lists

It's possible to use slicing:

```
print(mylist3[0:3])  
print(mylist3)
```

To change the value of an element in a list, simply assign it a new value:

```
mylist3[0] = 10  
print(mylist3)
```

Python - lists

There's a function that returns the number of elements in a list

```
len(mylist2)
```

Check if a value exists in a list:

```
1 in mylist2
```

Delete an element

```
len(mylist2)  
del mylist2[0]  
print(mylist2)
```

Iterate over the elements of a list:

```
for x in mylist2:  
    print(x)
```

Python - lists

There are more functions

```
max(mylist), min(mylist)
```

It's possible to add new elements to a list:

```
my_list.append(new_item)
```

We know how to find if an element exists, there's a way to return the position of that element:

```
my_list.index(item)
```

Or how many times a given item appears in the list:

```
my_list.count(item)
```

Exercise:

create a 3 lists:

one list, x , holding numbers going from 0 to 100

one list, y_1 , holding $x*x$

one list, y_2 , holding $x*x*x$

write these out to a file with the format:

x, y_1, y_2

Python - user defined functions

User-defined functions are reusable code blocks; they only need to be written once, then they can be used multiple times. They can even be used in other applications, too.

These functions are very useful, from writing common utilities to specific business logic. These functions can also be modified per requirement. The code is usually well organized, easy to maintain, and developer-friendly.

As user-defined functions can be written independently, the tasks of a project can be distributed for rapid application development.

A well-defined and thoughtfully written user-defined function can ease the application development process.

Python - user defined functions

Step 1: Declare the function with the keyword `def` followed by the function name.

Step 2: Write the arguments inside the opening and closing parentheses of the function, and end the declaration with a colon.

Step 3: Add the program statements to be executed.

Step 4: End the function with/without return statement.

Python - user defined functions

```
def userDefFunction (arg1, arg2, arg3  
...):  
    program statement1  
    program statement3  
    program statement3  
    ....  
    return;
```

Exercise:

write a user defined function that accepts an integer as an argument then prints out that many number of prime numbers

Exercise:

write a user defined function that accepts an integer as a parameter then returns the next prime number.

Exercise:

A prime gap is the difference between two successive prime numbers. The n -th prime gap, denoted g_n or $g(p_n)$ is the difference between the $(n + 1)$ -th and the n -th prime numbers

Write a program that uses your prime number generator functions and print out the first set of prime numbers where the prime gap is greater than 13

Python - Anonymous Functions

type the following into a cell:

```
x = lamda a: a * 10
```

```
print (x(10))
```

Python - Anonymous Functions

try the following definition:

```
def myfunc(x):  
    return lambda a: a*x
```

```
y = myfunc(10)  
print (y(5))  
z = myfunc(100)  
print (z(5))
```


Questions? Comments?

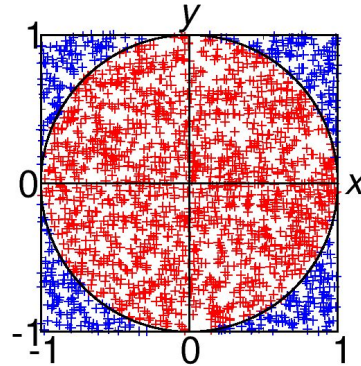
Monte Carlo Pi

Sequential Algorithm

A Monte Carlo algorithm for approximating π uniformly generates the points in the square $[-1, 1] \times [-1, 1]$. Then it counts the points which lie in the inside of the unit circle.

Sequential Algorithm

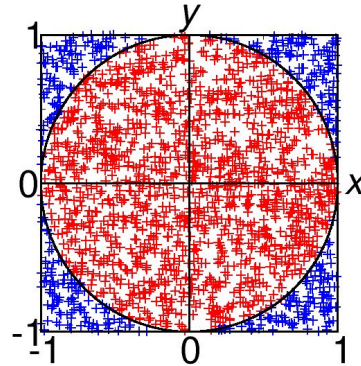
A Monte Carlo algorithm for approximating π uniformly generates the points in the square $[-1, 1] \times [-1, 1]$. Then it counts the points which lie in the inside of the unit circle.



Sequential Algorithm

An approximation of π is then computed by the following formula:

$$4 * \frac{\text{number of points inside}}{\text{total number of points}}$$



Algorithm

```
double approximatePi(int numSamples)
{
    float x, y;
    int counter = 0;
    for (int s = 0; s != numSamples; s++)
    {
        x = random number between -1, 1;
        y = random number between -1, 1;

```

```
        if (x * x + y * y < 1)
        {
            counter++;
        }
    }
    return 4.0 * counter / numSamples;
}
```

Let's code this in Python, Google to see what command in Python produces a random number

Linear Algebra

Applications

- Matrices in Engineering, such as a line of springs.
- Graphs and Networks, such as analyzing networks.
- Markov Matrices, Population, and Economics, such as population growth.
- Linear Programming, the simplex optimization method.
- Fourier Series: Linear Algebra for functions, used widely in signal processing.
- Linear Algebra for statistics and probability, such as least squares for regression.
- Computer Graphics, such as the various translation, rescaling and rotation of images.

Linear Algebra

Linear algebra is about linear combinations.

Using math on columns of numbers called vectors and arrays of numbers called matrices to create new columns and arrays of numbers.

Linear algebra is the study of lines and planes, vector spaces and mappings that are required for linear transforms.

Linear Algebra

Linear algebra is the mathematics of data.
Matrices and vectors are the language of data.

Let's look at the following:

$$y = 4 * x + 1$$

describes a line on a two-dimensional graph

Linear Algebra

Linear algebra is the mathematics of data.
Matrices and vectors are the language of data.

Let's look at the following:

$$\begin{aligned} \mathbf{y} &= 0.1 * \mathbf{x1} + 0.4 * \mathbf{x2} \\ \mathbf{y} &= 0.3 * \mathbf{x1} + 0.9 * \mathbf{x2} \end{aligned}$$

line up a system of equations with the same form with two or more unknowns

Linear Algebra

Linear algebra is the mathematics of data.
Matrices and vectors are the language of data.

Let's look at the following:

$$\begin{aligned} 1 &= 0.1 * x1 + 0.4 * x2 \\ 3 &= 0.3 * x1 + 0.9 * x2 \end{aligned}$$

line up a system of equations with the same form with two or more unknowns

Linear Algebra

Linear algebra is the mathematics of data.
Matrices and vectors are the language of data.

Let's look at the following, $Ax = b$:

$$\begin{aligned}5 &= 0.1 * x_1 + 0.4 * x_2 + x_3 \\10 &= 0.3 * x_1 + 0.9 * x_2 + 2.0 * x_3 \\3 &= 0.2 * x_1 + 0.3 * x_2 - .5 * x_3\end{aligned}$$

Is there a x_1, x_2, x_3 that solves this system?

Linear Algebra

Gaussian Elimination

The goals of Gaussian elimination are to make the upper-left corner element a 1

use elementary row operations to get 0s in all positions underneath that first 1

get 1s for leading coefficients in every row diagonally from the upper-left to lower-right corner, and get 0s beneath all leading coefficients.

you eliminate all variables in the last row except for one, all variables except for two in the equation above that one, and so on and so forth to the top equation, which has all the variables. Then use back substitution to solve for one variable at a time by plugging the values you know into the equations from the bottom up..

Linear Algebra

Gaussian Elimination, Rules

- You can multiply any row by a constant (other than zero).
- $-2r_3 \rightarrow r_3$
- You can switch any two rows.
- $r_1 \leftrightarrow r_2$
- You can add two rows together.
- $r_1 + r_2 \rightarrow r_2$

Linear Algebra

Transpose

A defined matrix can be transposed, which creates a new matrix with the number of columns and rows flipped.

This is denoted by the superscript “T” next to the matrix.

An invisible diagonal line can be drawn through the matrix from top left to bottom right on which the matrix can be flipped to give the transpose.

Linear Algebra

Inversion

Matrix inversion is a process that finds another matrix that when multiplied with the matrix, results in an identity matrix.

Given a matrix A , find matrix B , such that AB or $BA = I_n$.

The operation of inverting a matrix is indicated by a -1 superscript next to the matrix; for example, A^{-1} . The result of the operation is referred to as the inverse of the original matrix; for example, B is the inverse of A .

Linear Algebra

Trace

A trace of a square matrix is the sum of the values on the main diagonal of the matrix (top-left to bottom-right).

Linear Algebra

Determinant

The determinant of a square matrix is a scalar representation of the volume of the matrix.

The determinant describes the relative geometry of the vectors that make up the rows of the matrix. More specifically, the determinant of a matrix A tells you the volume of a box with sides given by rows of A .

— Page 119, [No Bullshit Guide To Linear Algebra](#), 2017

Linear Algebra

Matrix Rank

The rank of a matrix is the estimate of the number of linearly independent rows or columns in a matrix.

Linear Algebra - Matrix Arithmetic

Matrix Addition

Two matrices with the same dimensions can be added together to create a new third matrix.

$$C = A + B \quad C[0,0] = A[0,0] + B[0,0]$$

$$C[1,0] = A[1,0] + B[1,0]$$

$$C[2,0] = A[2,0] + B[2,0]$$

$$C[0,1] = A[0,1] + B[0,1]$$

$$C[1,1] = A[1,1] + B[1,1]$$

$$C[2,1] = A[2,1] + B[2,1]$$

Linear Algebra - Matrix Arithmetic

Matrix Subtraction

Similarly, one matrix can be subtracted from another matrix with the same dimensions.

$$C = A - B$$

$$C[0,0] = A[0,0] - B[0,0]$$

$$C[1,0] = A[1,0] - B[1,0]$$

$$C[2,0] = A[2,0] - B[2,0]$$

$$C[0,1] = A[0,1] - B[0,1]$$

$$C[1,1] = A[1,1] - B[1,1]$$

$$C[2,1] = A[2,1] - B[2,1]$$

Linear Algebra - Matrix Arithmetic

Matrix Multiplication (Hadamard Product)

Two matrices with the same size can be multiplied together, and this is often called element-wise matrix multiplication or the Hadamard product.

It is not the typical operation meant when referring to matrix multiplication, therefore a different operator is often used, such as a circle “o”.

$$\begin{aligned}C &= A \circ B \\C[0,0] &= A[0,0] * B[0,0] \\C[1,0] &= A[1,0] * B[1,0] \\C[2,0] &= A[2,0] * B[2,0] \\C[0,1] &= A[0,1] * B[0,1] \\C[1,1] &= A[1,1] * B[1,1] \\C[2,1] &= A[2,1] * B[2,1]\end{aligned}$$

Linear Algebra - Matrix Arithmetic

Matrix Division

One matrix can be divided by another matrix with the same dimensions.

$$\begin{aligned}C &= A / B \\C[0,0] &= A[0,0] / B[0,0] \\C[1,0] &= A[1,0] / B[1,0] \\C[2,0] &= A[2,0] / B[2,0] \\C[0,1] &= A[0,1] / B[0,1] \\C[1,1] &= A[1,1] / B[1,1] \\C[2,1] &= A[2,1] / B[2,1]\end{aligned}$$

Linear Algebra - Matrix Arithmetic

Matrix-Matrix Multiplication (Dot Product)

Matrix multiplication, also called the matrix dot product is more complicated than the previous operations and involves a rule as not all matrices can be multiplied together.

One of the most important operations involving matrices is multiplication of two matrices. The matrix product of matrices A and B is a third matrix C . In order for this product to be defined, A must have the same number of columns as B has rows. If A is of shape $m \times n$ and B is of shape $n \times p$, then C is of shape $m \times p$.

— Page 34, [Deep Learning](#), 2016.

Linear Algebra - Matrix Arithmetic

Matrix-Matrix Multiplication (Dot Product)

$$\mathbf{A} = \begin{matrix} a_{11}, & a_{12} \\ a_{21}, & a_{22} \\ a_{31}, & a_{32} \end{matrix}$$

$$\mathbf{B} = \begin{matrix} b_{11}, & b_{12} \\ b_{21}, & b_{22} \end{matrix}$$

$$\mathbf{C} = \begin{matrix} a_{11} * b_{11} + a_{12} * b_{21}, & a_{11} * b_{12} + a_{12} * b_{22} \\ a_{21} * b_{11} + a_{22} * b_{21}, & a_{21} * b_{12} + a_{22} * b_{22} \\ a_{31} * b_{11} + a_{32} * b_{21}, & a_{31} * b_{12} + a_{32} * b_{22} \end{matrix}$$

Numerical Linear Algebra, Two Different Approaches

- Solve $Ax = b$
- Direct methods:
 - Deterministic
 - Exact up to machine precision
 - Expensive (in time and space)
- Iterative methods:
 - Only approximate
 - Cheaper in space and (possibly) time
 - Convergence not guaranteed

Iterative Methods

Choose any x_0 and repeat

until

$$x^{k+1} = Bx^k + c$$

$$\|x^{k+1} - x^k\|_2 < \epsilon$$

or until

$$\frac{\|x^{k+1} - x^k\|_2}{\|x^k\|} < \epsilon$$

Example of Iterative Solution

Example system

$$\begin{pmatrix} 10 & 0 & 1 \\ 1/2 & 7 & 1 \\ 1 & 0 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 21 \\ 9 \\ 8 \end{pmatrix}$$

with solution (2,1,1)

Suppose you know (physics) that solution components are roughly the same size, and observe the dominant size of the diagonal, then

$$\begin{pmatrix} 10 & & \\ & 7 & \\ & & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 21 \\ 9 \\ 8 \end{pmatrix}$$

might be a good approximation. Solution (2.1, 2/7, 3/6)

Iterative Example

Example system

$$\begin{pmatrix} 10 & 0 & 1 \\ 1/2 & 7 & 1 \\ 1 & 0 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 21 \\ 9 \\ 8 \end{pmatrix}$$

with solution (2,1,1)

Also easy to solve:

$$\begin{pmatrix} 10 & & \\ 1/2 & 7 & \\ 1 & 0 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 21 \\ 9 \\ 8 \end{pmatrix}$$

with solution (2.1, 7.95/1, 5.9/6)

Iterative Example

- Instead of solving $Ax = b$ we solved $L\tilde{x} = b$.
- Look for the missing part: $\tilde{x} = x + \Delta x$, then $A\Delta x = A\tilde{x} - b \equiv r$
- Solve again $L\widetilde{\Delta x} = r$ and update $\tilde{\tilde{x}} = \tilde{x} - \widetilde{\Delta x}$

iteration	1	2	3
x_1	2.1000	2.0017	2.000028
x_2	1.1357	1.0023	1.000038
x_3	0.9833	0.9997	0.999995

- Two decimals per iteration. *This is not typical*
- Exact system solving: $O(n^3)$ cost; iteration: $O(n^2)$ per iteration. Potentially cheaper if the number of iterations is low.

Abstract Presentation

- To solve $Ax = b$; too expensive; suppose $K \approx A$ and solving $Kx = b$ is possible
- Define $Kx_0 = b$, then error correction $x_0 = x + e_0$, and $A(x_0 - e_0) = b$
- so $Ae_0 = Ax_0 - b = r_0$; this is again unsolvable, so
- $K\tilde{e}_0$ and $x_1 = x_0 - \tilde{e}_0$
- Now iterate: $e_1 = x_1 - x$, $Ae_1 = Ax_1 - b = r_1$ et cetera

Error Analysis

- One step $r_1 = Ax_1 - b = A(x_0 - \tilde{e}_0) - b$ (2)

$$= r_0 - AK^{-1}r_0 \quad (3)$$

$$= (I - AK^{-1})r_0 \quad (4)$$

- Inductively:
- Geometric reduction (of approximation): $r_n = (I - AK^{-1})^n r_0$ so $r_n \downarrow 0$ if $|\lambda(I - AK^{-1})| < 1$
- This is 'stationary iteration': every iteration step the same. Simple analysis, limited applicability

Computationally

If $A = K - N$

then $Ax = b \implies Kx = Nx + b \implies Kx_{i+1} = Nx_i + b$

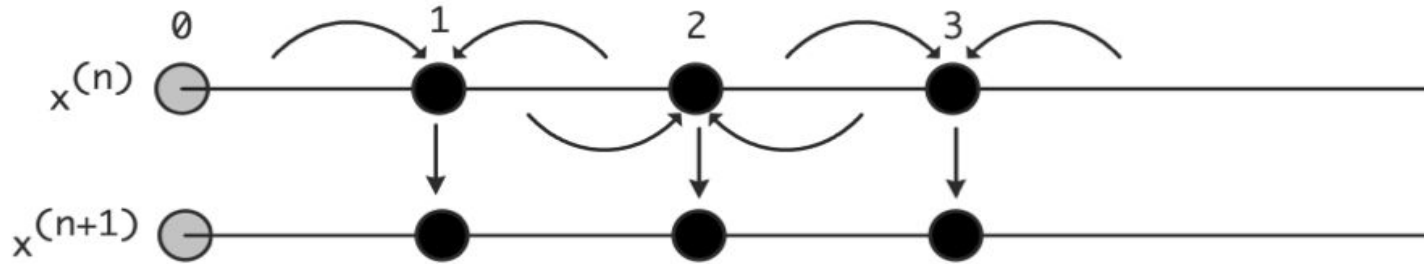
(because $Kx = Nx + b$ is a "fixed point" of an iteration)

Equivalent to the above, and you don't actually need to form the residual

Choice of K

- The closer K is to A , the faster the convergence
- Diagonal and lower triangular choice mentioned above: let $A = D_A + L_A + U_A$ be a splitting into diagonal, lower triangular, upper triangular part, then
- Jacobi method: $K = D_A$ (diagonal part),
- Gauss-Seidel method: $K = D_A + L_A$ (lower triangle, including diagonal)
- SOR method:
$$K = \omega D_A + L_A$$

Jacobi in Pictures



Jacobi Method

Given a square system of n linear equations:

$$A\mathbf{x} = \mathbf{b}$$

where:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

Jacobi Method

Then A can be decomposed into a diagonal component D , and the remainder R :

$$A = D + R \quad \text{where} \quad D = \begin{bmatrix} a_{11} & 0 & \cdots & 0 \\ 0 & a_{22} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_{nn} \end{bmatrix} \quad \text{and} \quad R = \begin{bmatrix} 0 & a_{12} & \cdots & a_{1n} \\ a_{21} & 0 & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & 0 \end{bmatrix}.$$

Jacobi Method

The solution is then obtained iteratively via

$$\mathbf{x}^{(k+1)} = D^{-1}(\mathbf{b} - R\mathbf{x}^{(k)}),$$

where $\mathbf{x}^{(k)}$ is the k th approximation or iteration of \mathbf{x} and $\mathbf{x}^{(k+1)}$ is the next or $k + 1$ iteration of \mathbf{x} . The element-based formula is thus:

$$x_i^{(k+1)} = \frac{1}{a_{ii}} \left(b_i - \sum_{j \neq i} a_{ij} x_j^{(k)} \right), \quad i = 1, 2, \dots, n.$$

The computation of $x_i^{(k+1)}$ requires each element in $\mathbf{x}^{(k)}$ except itself. Unlike the Gauss–Seidel method, we can't overwrite $x_i^{(k)}$ with $x_i^{(k+1)}$, as that value will be needed by the rest of the computation. The minimum amount of storage is two vectors of size n .

Jacobi Method

Algorithm.

- Choose your initial guess, $x[0]$
- Start iterating, $k=0$
 - While not converged do
 - Start your i-loop (for $i = 1$ to n)
 - $\text{sigma} = 0$
 - Start your j-loop (for $j = 1$ to n)
 - If j not equal to i
 - $\text{sigma} = \text{sigma} + a[i][j] * x[j]_k$
 - End j-loop
 - $x[i]_k = (b[i] - \text{sigma})/a[i][i]$
 - End i-loop
 - Check for convergence
 - Iterate k , ie. $k = k+1$

What about the Lower and Upper Triangles?

If we write D , L , and U for the diagonal, strict lower triangular and strict upper triangular and parts of A , respectively,

$$D = \begin{bmatrix} a_{11} & 0 & \cdots & 0 \\ 0 & a_{22} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & a_{nn} \end{bmatrix}, \quad L = \begin{bmatrix} 0 & 0 & \cdots & 0 \\ a_{21} & 0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ a_{n1} & \cdots & a_{nn-1} & 0 \end{bmatrix} \quad \text{and} \quad U = \begin{bmatrix} 0 & a_{12} & \cdots & a_{1n} \\ 0 & 0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & a_{n-1n} \\ 0 & \cdots & 0 & 0 \end{bmatrix},$$

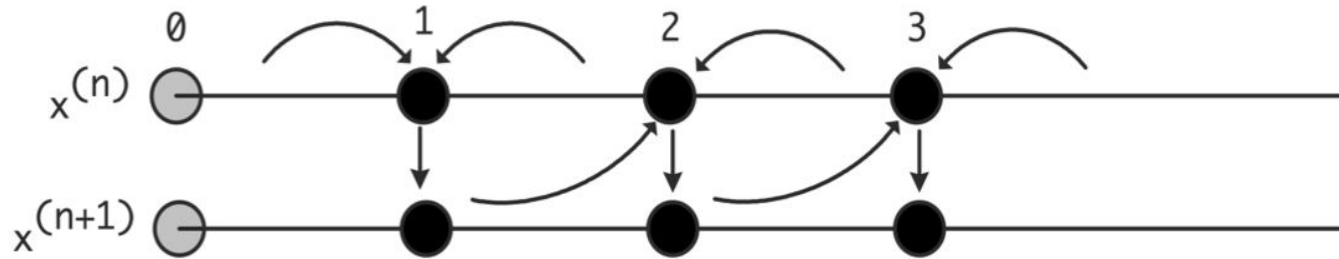
then Jacobi's Method can be written in matrix-vector notation as

$$D\mathbf{x}^{(k+1)} + (L+U)\mathbf{x}^{(k)} = \mathbf{b}$$

so that

$$\mathbf{x}^{(k+1)} = D^{-1}[(-L-U)\mathbf{x}^{(k)} + \mathbf{b}].$$

GS in Pictures



Gauss-Seidel

$$K = D_A + L_A$$


Algorithm:

for $k = 1, \dots$ until convergence, do:

for $i = 1 \dots n$:

$$\begin{aligned} // a_{ii}x_i^{(k+1)} + \sum_{j<i} a_{ij}x_j^{(k+1)} &= \sum_{j>i} a_{ij}x_j^{(k)} + b_i \Rightarrow \\ x_i^{(k+1)} &= a_{ii}^{-1}(-\sum_{j<i} a_{ij}x_j^{(k+1)}) - \sum_{j>i} a_{ij}x_j^{(k)} + b_i \end{aligned}$$

Implementation:

for $k = 1, \dots$ until convergence, do:

for $i = 1 \dots n$:

$$x_i = a_{ii}^{-1}(-\sum_{j \neq i} a_{ij}x_j + b_i)$$

$$\begin{aligned} Ax=b &\Rightarrow (D_A + L_A + U_A)x=b \\ (D_A + L_A)x^{k+1} &= -U_Ax^k + b \\ \{D_A\}_{ii} &= a_{ii} \quad \{U_A \text{ or } L_A\}_{ij} = a_{ij} \quad i \neq j \end{aligned}$$

Gauss-Seidel Method

Given a square system of n linear equations:

$$A\mathbf{x} = \mathbf{b}$$

where:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

Gauss-Seidel Method

$$A = L_* + U \quad \text{where} \quad L_* = \begin{bmatrix} a_{11} & 0 & \cdots & 0 \\ a_{21} & a_{22} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}, \quad U = \begin{bmatrix} 0 & a_{12} & \cdots & a_{1n} \\ 0 & 0 & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix}.$$

The system of linear equations may be rewritten as:

$$L_* \mathbf{x} = \mathbf{b} - U \mathbf{x}$$

Gauss-Seidel Method

It is defined by the iteration

$$L_* \mathbf{x}^{(k+1)} = \mathbf{b} - U \mathbf{x}^{(k)},$$

where $\mathbf{x}^{(k)}$ is the k th approximation or iteration of \mathbf{x} , $\mathbf{x}^{(k+1)}$ is the next or $k + 1$ iteration of \mathbf{x} , and the matrix A is decomposed into a lower triangular component L_* , and a strictly upper triangular component U : $A = L_* + U$.^[2]

Which gives us:
$$\mathbf{x}^{(k+1)} = L_*^{-1}(\mathbf{b} - U \mathbf{x}^{(k)}).$$

However, by taking advantage of the triangular form of L_* , the elements of $\mathbf{x}^{(k+1)}$ can be computed sequentially using forward substitution:

$$x_i^{(k+1)} = \frac{1}{a_{ii}} \left(b_i - \sum_{j < i} a_{ij} x_j^{(k+1)} - \sum_{j > i} a_{ij} x_j^{(k)} \right), \quad i, j = 1, 2, \dots, n.$$

Gauss-Seidel Method

Algorithm:

- Choose your initial guess, $\theta[0]$
- While not converged do:
 - Start your i-loop (for $i = 1$ to n)
 - $\sigma = 0$
 - Start your j-loop (for $j = 1$ to n)
 - If j not equal to i
 - $\sigma = \sigma + a[i][j] * \theta[j]$
 - End j-loop
 - $\theta[i] = (b[i] - \sigma) / a[i][i]$
 - End i-loop
 - Check for convergence
 - iterate

Stopping Tests

When to stop converging? Can size of the error be guaranteed?

- Direct tests on error $e_n = x - x_n$ impossible; two choices
- Relative change in the computed solution small:

$$\|x_{n+1} - x_n\| / \|x_n\| < \epsilon$$

- Residual small enough:

$$\|r_n\| = \|Ax_n - b\| < \epsilon$$

Without proof: both ϵ and ϵ' some other

ϵ'

Python - NumPy

"Numerical Python"

open source extension module for Python
provides fast precompiled functions for
mathematical and numerical routines
adds powerful data structures for efficient
computation of multi-dimensional arrays and
matrices.

NumPy, First Steps

Let build a simple list, turn it into a numpy array and perform some simple math.

```
import numpy as np
cvalues = [25.3, 24.8, 26.9, 23.9]
C = np.array(cvalues)
print(C)
```

NumPy, First Steps

Let build a simple list, turn it into a numpy array and perform some simple math.

```
print(C * 9 / 5 + 32)
```

vs.

```
fvalues = [ x*9/5 + 32 for x in cvalues ]  
print(fvalues)
```

NumPy, Cooler things

```
import time
size_of_vec = 1000
def pure_python_version():
    t1 = time.time()
    X = range(size_of_vec)
    Y = range(size_of_vec)
    Z = []
    for i in range(len(X)):
        Z.append(X[i] + Y[i])
    return time.time() - t1
```

```
def numpy_version():
    t1 = time.time()
    X = np.arange(size_of_vec)
    Y = np.arange(size_of_vec)
    Z = X + Y
    return time.time() - t1
```

NumPy, Cooler things

Let's see which is faster.

```
t1 = pure_python_version()
t2 = numpy_version()
print(t1, t2)
```

NumPy, Multi-Dimension Arrays

```
A = np.array([ [3.4, 8.7, 9.9],
               [1.1, -7.8, -0.7],
               [4.1, 12.3, 4.8]])

print(A)
print(A.ndim)

B = np.array([ [[111, 112], [121, 122]],
               [[211, 212], [221, 222]],
               [[311, 312], [321, 322]] ])

print(B)
print(B.ndim)
```

NumPy, Multi-Dimension Arrays

The shape function:

```
x = np.array([ [67, 63, 87],  
               [77, 69, 59],  
               [85, 87, 99],  
               [79, 72, 71],  
               [63, 89, 93],  
               [68, 92, 78]])  
print(np.shape(x))
```

NumPy, Multi-Dimension Arrays

The shape function can also *change* the shape:

```
x.shape = (3, 6)  
print(x)
```

```
x.shape = (2, 9)  
print(x)
```

NumPy, Multi-Dimension Arrays

A couple more examples of shape:

```
x = np.array(42)
print(np.shape(x))

B = np.array([ [111, 112], [121, 122]],
              [[211, 212], [221, 222]],
              [[311, 312], [321, 322]] ])
print(B.shape)
```


NumPy, Multi-Dimension Arrays

indexing:

```
F = np.array([1, 1, 2, 3, 5, 8, 13, 21])

# print the first element of F, i.e. the element with the index 0
print(F[0])

# print the last element of F
print(F[-1])

B = np.array([ [111, 112], [121, 122]],
              [[211, 212], [221, 222]],
              [[311, 312], [321, 322]] ])
print(B[0][1][0])
```

NumPy, Multi-Dimension Arrays

slicing:

```
A = np.array([
    [11,12,13,14,15],
    [21,22,23,24,25],
    [31,32,33,34,35],
    [41,42,43,44,45],
    [51,52,53,54,55]])

print(A[:3,2:])

print(A[3:,:])
```

NumPy, Multi-Dimension Arrays

function to create an identity array

```
np.identity(4)
```

NumPy, By Example

The example we will consider is a very simple (read, trivial) case of solving the 2D Laplace equation using an iterative finite difference scheme (four point averaging, Gauss-Seidel or Gauss-Jordan). The formal specification of the problem is as follows. We are required to solve for some unknown function $u(x,y)$ such that $\nabla^2 u = 0$ with a boundary condition specified. For convenience the domain of interest is considered to be a rectangle and the boundary values at the sides of this rectangle are given.

```
def TimeStep(self, dt=0.0):
    """Takes a time step using straight forward Python loops."""
    g = self.grid
    nx, ny = g.u.shape
    dx2, dy2 = g.dx**2, g.dy**2
    dnr_inv = 0.5/(dx2 + dy2)
    u = g.u
    err = 0.0
    for i in range(1, nx-1):
        for j in range(1, ny-1):
            tmp = u[i,j]
            u[i,j] = ((u[i-1, j] + u[i+1, j])*dy2 +
                    (u[i, j-1] + u[i, j+1])*dx2)*dnr_inv
            diff = u[i,j] - tmp
            err += diff*diff
    return numpy.sqrt(err)
```

NumPy, By Example

The example we will consider is a very simple (read, trivial) case of solving the 2D Laplace equation using an iterative finite difference scheme (four point averaging, Gauss-Seidel or Gauss-Jordan). The formal specification of the problem is as follows. We are required to solve for some unknown function $u(x,y)$ such that $\nabla^2 u = 0$ with a boundary condition specified. For convenience the domain of interest is considered to be a rectangle and the boundary values at the sides of this rectangle are given.

```
def numericTimeStep(self, dt=0.0):
    """Takes a time step using a NumPy expression."""
    g = self.grid
    dx2, dy2 = g.dx**2, g.dy**2
    dnr_inv = 0.5/(dx2 + dy2)
    u = g.u
    g.old_u = u.copy() # needed to compute the error.

    # The actual iteration
    u[1:-1, 1:-1] = ((u[0:-2, 1:-1] + u[2:, 1:-1])*dy2 +
                    (u[1:-1, 0:-2] + u[1:-1, 2:])*dx2)*dnr_inv

    return g.computeError()
```

NumPy, Exercise

Jacobi

Algorithm.

```
* Find D, the Diagonal of of A : diag(A)
* Find R, the Remainder of A - D : A - diagflat(A)

* Choose your initial guess, x[0]
  * Start iterating, k=0
    * While not converged do
      * Start your i-loop (for i = 1 to n)
        * sigma = 0
        * Start your j-loop (for j = 1 to n)
          * If j not equal to i
            * sigma = sigma + a[i][j] * x[j][k]
          * End j-loop
        * x[i]k = (b[i] - sigma)/a[i][i] : x = (b - dot(R,x)) / D
      * End i-loop
    * Check for convergence
  * Iterate k, ie. k = k+1
```

Questions? Comments?